USER MANUAL

Simpro Ezi-MT®



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For the purpose of standards compliance and international conformity, this document uses Système International (SI) units. These may be converted to their Imperial equivalents as follows:

1 kilogram (kg) = 2.2 pounds (lb)

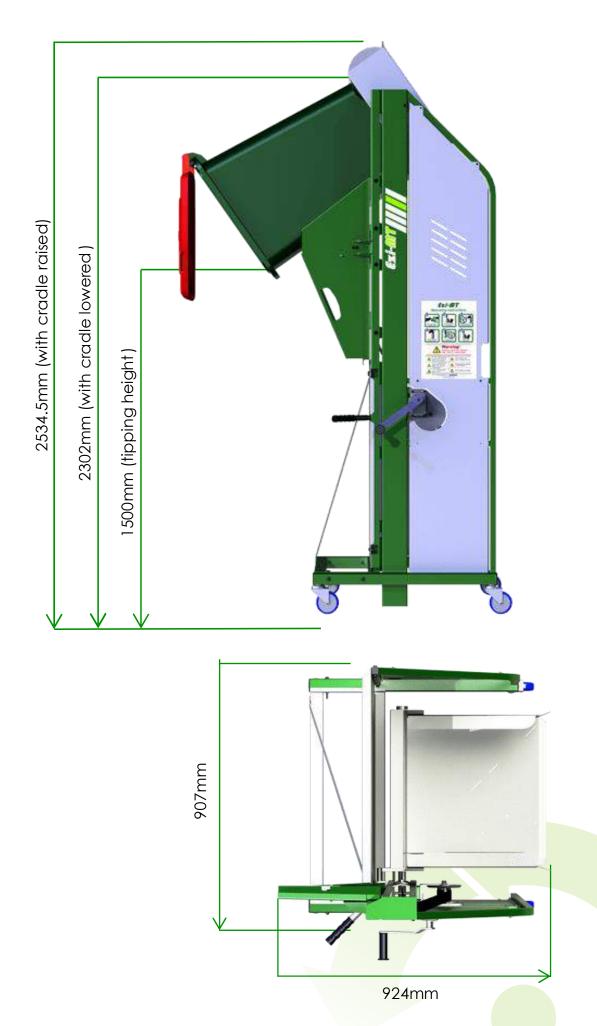
1 metre (m) = 1000 millimetres (mm) = 1.09 yards (yd) = 39.37 inches (in)

The following textual conventions are used throughout this document:

A Text in GREEN indicates a point of interest.

Text in RED indicates a point of warning, or a safety hazard.

Any errors in this document should be reported by email to info@simpro.world.



1 Contents

1	Con	tents	3
2	Intro	duction	5
	2.1	Key Features	6
	2.2	Construction	6
	2.3	Mechanism	6
	2.4	Environmental restrictions	6
	2.5	Intended operational life	6
	2.6	Layout of Parts	7
	2.7	Important notes	7
3	Safe	ty	9
	3.1	Safety features	9
	3.2	Reasonably foreseeable misuse	9
	3.3	Hazard and Risk Assessment	9
		3.3.1 Risk Evaluation guide	.10
		3.3.2 Identified Hazards	.11
	3.4	Residual Hazards	. 14
	3.5	Safety Norms	. 15
4	Оре	rating Instructions	.17
5	Mair	itenance Procedures	.19
	5.1	Quick Troubleshooting Guide	. 19
	5.2	Cleaning	. 19
		5.2.1 Ingress protection	.19
	5.3	Cradle jams	. 20
		5.3.1 Cradle jams while raising	.20
		5.3.2 Cradle jams while lowering	.20
	5.4	Winch and strap	. 20
6	Hand	dling, transportation and storage	.21
	6.1	Moving	. 21
	6.2	Lifting	. 21
	6.3	Transportation	. 21

	6.4 Storage	21
7	Safety Inspections	23
	7.1 Monthly inspection checklist	23
	7.2 Monthly inspection log	24
8	Spare Parts	25
9	Warranty	26

2 Introduction

Congratulations on your purchase of an Ezi-MT bin-tipping machine from Simpro. Ezi-MT is a light-duty manual bin tipper, designed for low volume users. It is environmentally friendly and perfect for those on constrained budgets, such as schools, cafes, small businesses, and local councils.

Ezi-MT uses the same reliable tipping action found on other Simpro products, but with a difference: it is powered by renewable energy, supplied by the user! The innovative hand-cranked design allows full workplace safety compliance, with no expensive hydraulic machinery.

Like other Simpro tippers, Ezi-MT always keeps the weight of the bin within the footprint of the machine to ensure stability. It can empty wheelie bins and carts weighing up to 65kg.

Whole-of-life environmental impact was considered from the start of the Ezi-MT design process, to create a truly eco-friendly product. The unique single-mast design uses 50% less steel than competing products, and is shipped flat-packed to reduce carbon emissions from shipping. The Ezi-MT has no powered components, generates no electronic waste, and is completely recyclable.

Yet the Ezi-MT is also remarkably durable and can be used outdoors for many years with little or no maintenance.

As workplace safety becomes ever more important, the Simpro Ezi-MT means there is no longer any excuse for lifting your heavy waste bins by hand!

2.1 Key Features

Key features of the Ezi-MT include:

- A unique tipping action whereby bins are lifted straight up, and then gently rolled forward around the lip of the container being emptied into. This allows for a small floor 'footprint' yet very high stability.
- 2. The ability to safely lift bins weighing up to 65kg.
- 3. A simple and reliable design requiring virtually no maintenance.
- 4. A lightweight design with large castor wheels and grab handles to allow for easy movement on any terrain.
- 5. Full corrosion protection applied to all steel components, allowing the machine to be used indoors or out.
- 6. A modular cradle design which can be easily adapted to suit a wide range of bin sizes, shapes, and weights.
- 7. Standard EN840 bins do not require clamping or retaining simply place on the cradle and empty.

2.2 Construction

The Ezi-MT machine consists of a steel frame with one vertical mast, a steel bin cradle and sheet-metal guarding, one braked winch, one grab handle and four castor wheels.

2.3 Mechanism

When the winch handle is turned clockwise, a nylon lifting strap is pulled through a roller to raise the bin cradle. The cradle moves vertically in the mast and is inverted at the appropriate height by a 'follower roller' running in a 'guide track'. The winch is geared and has an automatic brake which applies as soon as the handle is released. This allows the operator to raise and lower the bin in a controlled manner.

2.4 Environmental restrictions

The Ezi-MT may be used indoors or outdoors. However, the following restrictions apply:

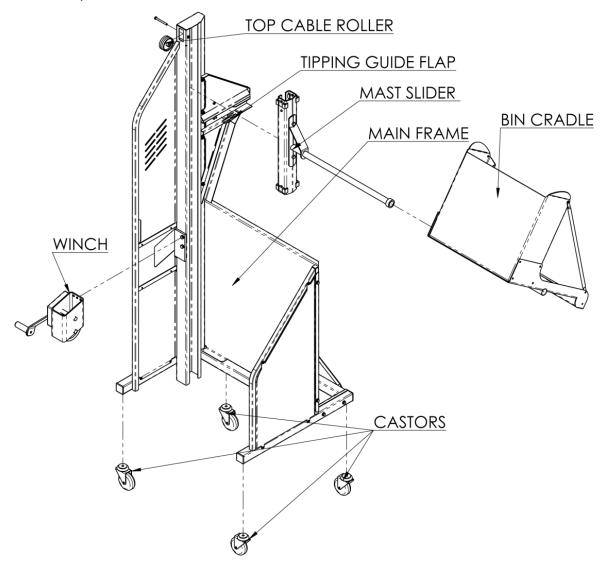
- 1. A minimum floor area of two square metres, with a clear passage to exits;
- 2. Ambient temperature not lower than -10°C or higher than +50°C.
- 3. Do not use in corrosive, acidic or alkaline environments.

2.5 Intended operational life

The intended operational life of the Ezi-MT is as follows:

Average Gross Bin Weight	Intended operational life
< 30kg	25,000 cycles
30kg – 65kg	10,000 cycles
> 65kg	5,000 cycles

2.6 Layout of Parts



2.7 Important notes

- A This user manual describes approved procedures for the operation, maintenance, and routine inspection of the Ezi-MT bin-tipping machine.
- All operators must carefully read and understand this manual before using the machine.
- A The user manual shall be kept by the operator, and shall be read by the operator until the operator is proficient with all aspects of standard use.
- A If the machine is to be leased, then the user manual shall accompany the machine.
- A This is a common manual. We reserve the right to modify the design of the machine. If there is anything in the manual that is not consistent with the actual machine, the actual machine should be considered correct and the manual is only for reference.
- Any errors in this document should be reported by email to info@simpro.world.
- A Please contact your authorized Simpro agent if you encounter any problems.

3 Safety

The Ezi-MT has been designed to be as safe as possible without restricting the ease-of-use and versatility of the machine.



A comprehensive Hazard and Risk Assessment should be undertaken before the Ezi-MT is used for the first time, as described in <u>Section 3.3</u>.

Safety features 3.1

The safety features of the Ezi-MT are as follows:

- 1. A geared, braked winch which requires operator input both to raise and lower the cradle, and which immediately stops all movement as soon as the handle is released.
- 2. A sheet metal guard panel which physically prevents the operator from accessing moving parts while using the machine.
- 3. A tipping action which keeps the weight of the bin within the machine footprint at all times to ensure stability.

3.2 Reasonably foreseeable misuse

The reasonably foreseeable misuse considered in the Ezi-MT design is as follows:

- Use of the machine by untrained operators;
- 2. Failure to follow correct operating procedures;
- 3. Tipping bins that the cradle is not specifically designed to hold;
- 4. Use of the machine with a frayed strap, faulty or ineffective winch brake, or other items worn, missing, or out of adjustment.

3.3 Hazard and Risk Assessment

Machinery owners are required by law to conduct a comprehensive Hazard and Risk Assessment for their equipment, considering all relevant factors such as the area it is used, the skill and training of operators, the proximity of other persons, frequency of use, etc.

The following section is not a comprehensive site-specific Hazard and Risk Assessment, but an assessment of the generic risk factors associated with the Dumpmaster design. Blank template spaces are provided for the assessment of additional site-specific hazards.



As with all powered industrial equipment, some hazards will remain despite any precautions undertaken by the manufacturer or owner of the machine. It is essential that all operators are aware of these residual hazards and what they must do to prevent harm to themselves or to others, as described in Section 3.4.

3.3.1 Risk Evaluation guide

As defined by ISO safety standards, any given hazard has a numeric Risk Factor, from which is derived the final Risk Evaluation. These factors can be calculated as follows.

3.3.1.1 Risk Factor calculation

The Risk Factor associated with a given hazard may be calculated using the following table, with the formula: Risk Factor = LO x FE x DPH x NP

LO	Likelihood of Occurrence	FE	Frequency of Exposure	DPH	Degree of Possible Harm	NP	Number of Persons at risk
0.1	Impossible, or possible only in extreme circumstances	0.1	Infrequently	0.1	Scratch or bruise	1	1 – 2 persons
0.5	Highly unlikely though conceivable	0.2	Annually	0.5	Laceration, mild ill-health	2	3 – 7 persons
1	Unlikely but could occur	1	Monthly	1	Break minor bone or illness (temporary)	4	8 – 15 persons
2	Possible but unusual	1.5	Weekly	2	Break major bone or illness (permanent)	8	16 – 50 persons
5	Even chance – could happen	2.5	Daily	4	Loss of 1 limb or eye/serious illness (temporary)	12	51 or more persons
8	Probable – not surprised	4	Hourly	8	Loss of 2 limbs or eyes/serious illness (permanent)		
10	Likely, only to be expected	5	Constantly	15	Fatality		
15	Certain, no doubt						

3.3.1.2 Risk Evaluation

Once the Risk Factor has been calculated, the Risk Evaluation can be determined using the following table:

Risk Factor	0-1	2-5	6-10	11-50	51-100	101-500	501-1000	1001 +
Risk Evaluation	Negligible	Very Low	Low	Significant	High	Very high	Extreme	Unaccept able

3.3.2 *Identified Hazards*

The following common hazards have been identified with the Dumpmaster design. For each hazard, a full Risk Evaluation has been completed, and suitable control measures described.

A Blank template spaces are provided at the end for machinery owners to identify, assess and control additional site-specific hazards.

Entanglement	or amp	utation o	f fingers	or lim	bs in movin	g par	ts			
Operator	LO:	0.5	FE:	4	DPH:	1	NP:	1	Risk Factor:	2
					oing hazaro g parts whi				d it is difficult :	for
Other persons	LO:	1	FE:	4	DPH:	1	NP:	1	Risk Factor:	4
The operator has a good view of the cradle while lifting and lowering, a simply stop all movement by releasing the winch handle if any other pe approach the cradle while moving.									_	
Control measures	instructi	ions, reg	arding k	eepin	g himself ar	nd oth	ners clear	of all	machine and moving parts	S.
Comments	needed	d to easil	y opera	te the	machine.	ds are	minimize	d, and	d both hands	are
Crushing due	to unaut	horised r	apid de	scent	of cradle					
Operator	LO:	0.5	FE:	4	DPH:	1	NP:	1	Risk Factor:	2
	operati the cra	on. There	e is nothi it is inve	ng to erted.		erator safety	or other margins	perso	guarding duri n moving und e that the	-
Other persons	LO:	0.5	FE:	4	DPH:	1	NP:	1	Risk Factor:	2
	As above.									
Control measures	instructi the cra	ions, rego dle wher	arding ken n raised.	eepin	g himself ar	nd oth	ners away	from	machine and the area und sired immedia	der
Comments					aximum spe	eed o	f descent	t in no	rmal use.	
Operator or o		ng hit by		or flyin						
Operator	LO:	1	FE:	4	DPH:	0.5	NP:	1	Risk Factor:	2
					product su		broken g		guarding duri being tipped	
Other persons	LO:	1	FE:	4	DPH:	0.5	NP:	1	Risk Factor:	2
	tipped.				, .				glass is being	
Control measures	keeping	g himself	and oth	ers av	vay from th	ie ma	chine wh	ile in ù	g signs regard use. ves should be	Ū
Comments										

Crushing due	to mach	ine fallin	a over							
Operator	LO:	0.5	FE:	2.5	DPH:	1	NP:	1	Risk Factor:	1.25
		Low risk as the machine is very stable and the bin centre of gravity remains well within the machine's footprint throughout the tipping cycle.								
Other persons	LO:	0.5	FE:	2.5	DPH:	1	NP:	1	Risk Factor:	1.25
	As abo	ve.								
Control measures					ound, or gr ds from clos			pe of	more than 1	:12.
Comments										
Contamination									D: 1	
Operator	LO:	2	FE:	4	DPH:	1	NP:	1	Risk Factor:	8
	windy o	condition	s. If the ny othe	produ	-	ause c	ıny harm	whats	ped, especi soever to the le Personal	
Other persons	LO:	2	FE:	4	DPH:	1	NP:	1	Risk Factor:	8
	As abo									
Control measures	and en Powde installed	sure that r should o d.	all othe only be	er perse tipped	ons are wel I in calm co	l clea onditio	r of the a ons, or a v	rea. vind s	ective Equip hield should	be
Comments			-		•		_		th PPE should nethods shou	
Use by untrain	ned or ur	nauthoris	ed oper	ators						
Operator	LO:	2	FE:	4	DPH:	1	NP:	1	Risk Factor:	8
	operate	e the ma	chine. It	t is the		ty of e	end users		attempting sure the Ezi- <i>l</i>	
Other persons	LO:	2	FE:	4	DPH:	1	NP:	1	Risk Factor:	8
·	As abo	As above.								
Control measures	All persons must be trained in safe operating procedures before being authorised to use the machine. Additional control measures may include using a padlock and chain to disable the winch, or placing the machine in secure storage when not in use.									
Comments	storage The ma	when no	ot in use simple to	e. Diuse c		h, or ped wit	olacing th h large so	ne mo afety i	chine in sec	
Damage to sl	storage The ma operati cin when	when no contract when no contract when the contr	ot in use simple to trained extreme	e. D use c persoi	ole the winco and designents is unlikely ther condition	h, or ped with to re	olacing th h large so sult in inju	ne mo afety i	nchine in sec	ure
	storage The ma operati cin when LO:	when nachine is some by un	ot in use simple to trained extreme FE:	person weat	ole the winc and designents is unlikely ther condition DPH:	ed with to recons	nlacing the harge so sult in inju	ne mo afety i iry.	nchine in sec margins, so Risk Factor:	ure 8
Damage to sl	storage The mo operati cin when LO: If the m	when not chine is so on by unused in a 2	ot in use simple to trained extreme FE:	e. o use o person weat	ole the winc and designents is unlikely ther condition DPH:	ed with to recons	h large so sult in inju	ne mo	nchine in sec margins, so Risk	ure 8
Damage to sl	storage The mo operati cin when LO: If the m	when not chine is so on by un used in a 2	ot in use simple to trained extreme FE:	e. o use o person weat	ole the wincommoder designers is unlikely her condition DPH:	ed with to recons	h large so sult in inju	ne mo	nchine in sec margins, so Risk Factor:	ure 8
Damage to sl Operator	storage The mo operati cin when LO: If the m gloves	e when not chine is son by un used in a 2 and other 2	ot in use simple to trained extreme FE:	e weat 4 Use of Use of Used in le Pers	and designents is unlikely her condition DPH: a extreme condition of the	ed with to reconsult old or otive E	h large so sult in inju NP: heat, the	ne mo	rator must w	8 ear
Damage to sl Operator	storage The mo operati cin when LO: If the m gloves LO: As abo All pers	e when not contain the second of the second	ot in use simple to trained extreme FE: s to be user suitab FE: esponsit	person weath 4 used in le Pers	ole the wind and designents is unlikely her condition DPH: a extreme condition DPH:	ed with to reconsult of the ed with the ed	h large so sult in inju	afety in a property of the modern of the mod	Risk Factor: rator must w Risk Factor: ment suitable	8 ear

Site-specific	hazard:				
Operator	LO:	FE:	DPH:	NP:	Risk Factor:
Other	LO:	FE:	DPH:	NP:	Risk
persons					Factor:
Control measures					
Comments					
Site-specific					
Operator	LO:	FE:	DPH:	NP:	Risk Factor:
Other persons	LO:	FE:	DPH:	NP:	Risk Factor:
Caralnal					
Control measures					
Comments					
Site-specific	hazard:				
Operator	LO:	FE:	DPH:	NP:	Risk Factor:
Other	LO:	FE:	DPH:	NP:	Risk
persons	10.	۱ ۵۰	Di ii.	141.	Factor:
Caralnal					
Control measures					
Comments					
Site-specific	hazard:				
Operator	LO:	FE:	DPH:	NP:	Risk Factor:
Other persons	LO:	FE:	DPH:	NP:	Risk Factor:
Combined					
Control measures					
Comments					

3.4 Residual Hazards

As with all powered industrial equipment, some 'residual hazards' may be present despite any guarding or safety measures implemented by the manufacturer.

The operator has a legal responsibility to identify and assess these residual hazards, and to take **all reasonable precautions** to eliminate, isolate, or minimize them. Such precautions may include any or all of the following:

- A Procedures to record and monitor that operators are properly trained.
- Implementation of Standard Operating Procedures.
- A Disciplinary measures to ensure the Standard Operating Procedures are observed.
- A Posting signage, floor marking, or other warnings as deemed appropriate.
- ▲ Taking steps to develop a culture of safety and open communication among machinery operators.

3.5 Safety Norms

The following safety norms must always be observed for the safe use of a Ezi-MT bin lifter.

Only trained and authorised persons should be permitted to use the machine.

Operators must read and obey the instructions displayed on the machine.

Never operate the machine on ground with a slope ratio greater than 1:12.

Never operate the machine on the edge of a raised loading dock or platform.

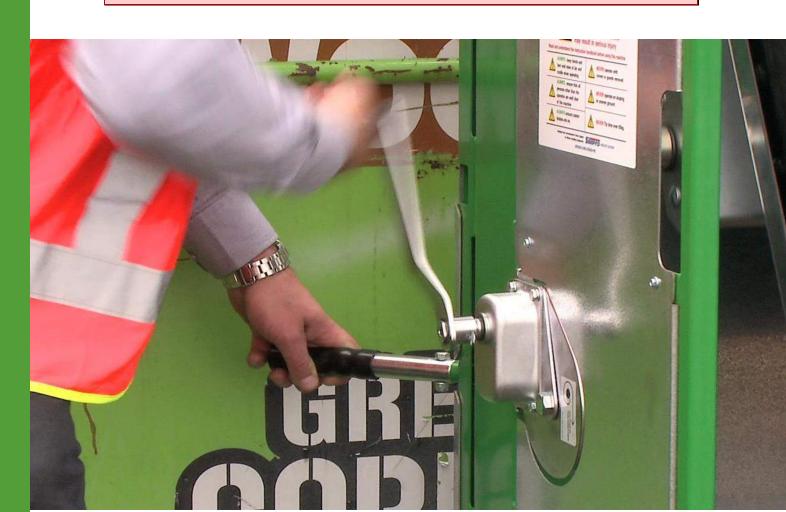
Never operate the machine with any covers or guards removed.

Never attempt to empty over-filled bins, or bins weighing more than 65kg. Never attempt to empty the contents of closedtop drums or bins. All persons other than the operator must keep at least 2 metres clear while the machine is in use. Always keep hands and feet well clear of the bin and cradle when operating. Never place feet or foreign objects under the side guard, frame or cradle.

4 Operating Instructions

How to operate a standard Ezi-MT bin lifter.

- 1. Before operation, check that the machine is stable and safe to use:
 - a. Machine is on level ground, with a slope of 1:12 or less.
 - b. All covers and safety guards are in place.
 - c. The lifting strap is not visibly torn or frayed.
 - d. Both wheel brakes are applied.
 - e. All personnel other than the operator are well clear of the machine.
 - f. The cradle is fully lowered.
- 2. Place the full bin on the cradle, taking care that it is properly positioned.
- 3. Brace your body by holding the grab-handle on the Ezi-MT mast with your left hand. Use your right hand to turn the winch handle in a clockwise direction until the bin reaches the inverted position.
- 4. When the contents of the bin have emptied, turn the winch handle in a counterclockwise direction until the cradle rests on the ground.
- 5. Remove the empty bin, and repeat from step 1) as required.
- When using a cradle with wheel-catches to empty EN840 wheelie bins of any size (60L/80L/120L/140L/240L), **only the left-hand wheel of the bin** needs to be placed into a wheel channel. The bins are still held securely using only one wheel.
- A The cradle may be stopped at any point of the cycle, by simply releasing the winch.



Ezi-MT

Operating Instructions















Warning!

Careless use of this machine may result in serious injury

Read and understand the instruction handbook before using this machine



ALWAYS keep hands and feet well clear of bin and cradle when operating



NEVER operate with covers or guards removed



ALWAYS ensure that all persons other than the operator are well clear of the machine



NEVER operate on sloping or uneven ground



ALWAYS ensure castor brakes are on.



NEVER Tip bins over 65kg.

5 Maintenance Procedures

The Ezi-MT is designed to give many years of service with minimal maintenance. In the event a fault or malfunction does occur, refer to the <u>Quick Trouble Shooting Guide in Section 5.1</u> before contacting your agent for service.

- A Contact your Simpro agent if repair or service work is required.
- All repair and service work must be carried out by qualified personnel.
- A Replacement parts must be supplied by Simpro or an authorized Simpro agent, and must be of the same design and specification as the original parts.
- A detailed Service Manual giving specific testing and repair instructions is available on request from Simpro.

5.1 Quick Troubleshooting Guide

Refer to the Quick Trouble Shooting Guide below before contacting your agent for service.

Problem	Possible Causes	Remedy
	Bin too heavy	Remove material from bin to reduce the weight
The machine will not lift bins	Winch broken	Repair or replace winch – contact your agent
	Lifting strap broken	Replace lifting strap – contact your agent
Cradle will not come down from the fully raised position	Mast slider frame jamming in mast	Lightly lubricate inside of mast with silicone spray Lubricate follower roller
The folly raised position	Bin too heavy Winch broken Lifting strap broken Mast slider frame	Repair or replace winch – contact your agent
		Check and rectify; contact your agent if necessary
Cradle jams part way down	, , ,	Check and rectify; contact your agent if necessary

5.2 Cleaning

The Ezi-MT may be cleaned with a low-pressure water jet, a cloth and a mild cleaning solution. Cleaning should be done with the cradle in the fully lowered position.

▲ Do not clean the Ezi-MT with a high-pressure water jet or waterblaster.

5.2.1 Ingress protection

5.2.12g. 666 p. 6 666.6				
Item	Ingress Protection			
Overall Rating	IP66			

5.3 Cradle jams

Occasionally the bin cradle may become jammed at some point in the tipping cycle. This is usually a minor issue which may be easily rectified.

The cradle is not pulled or powered down – it is lowered by gravity alone.

lack A Never place any part of your body underneath the raised cradle, unless it is securely supported by a hoist, forklift, or other suitable arrangement.

5.3.1 *Cradle jams while raising*

If the cradle jams while being raised, the cause is usually due to the bin being too heavy, or all the weight being at the bottom of the bin (rather than evenly distributed).

- 1. Lower the cradle to ground level if possible.
- 2. Remove some of the product manually, then try again.
- 3. If the cradle jams even with a light bin or no bin at all, attempt to identify the cause, and rectify with reference to the Service Manual (available on request from Simpro).

5.3.2 *Cradle jams while lowering*

If the cradle jams while lowering, or has jammed on the way up but will not come down, the cause will most likely be a mechanical fault. Use the following procedure to rectify the problem:

- 1. Manually empty the bin if there is any product remaining in it.
- 2. Attempt to identify the cause of the jamming. The most likely causes are:
 - a. The flap in the 'tipping guide' may not be working correctly. When lowering, a small pin on the cradle should lift the flap just before the follower roller reaches the flap. If not, check that the pin has not been bent or broken.
 - b. The shaft collar holding the cradle on the main axle may have moved, allowing the follower roller to come out of the 'tipping guide' track.
 - c. The mast may have been bent or damaged, causing a mast 'sliding block' to jam.
 - d. Lack of lubrication in the mast.
- 3. Once the problem has been identified, rectify it, then lower the cradle to the ground.
- 4. Raise and lower the cradle several times with no load to ensure the problem has been properly resolved. Then also test with a full load.
- 5. If there are no further problems, the machine may be returned to service.

5.4 Winch and strap

The Ezi-MT is fitted with a high-quality industrial braked winch and a black nylon lifting strap. The winch uses an internal reduction gear arrangement, allowing the user to lift heavy bins.

The winch and lifting strap are suitable for outdoors use, and require no regular maintenance.

A If the winch is damaged or malfunctioning, or the lifting strap is visibly frayed, it should be replaced. Contact your agent for a replacement strap.

6 Handling, transportation and storage

6.1 Moving

The Ezi-MT can be easily moved on its castor wheels, using the large grab handles provided. The cradle should be just off the ground when moving the machine.

Extra care should be taken when moving the Ezi-MT on sloping ground.



 \mathbb{A} A small accessory is available from Simpro which enables a directional lock on any or all of the castor wheels. In some cases this makes the machine easier to manoeuvre.

6.2 Lifting

Observe the following procedure when lifting, loading or unloading the Ezi-MT:

- 1. Ensure the lifting equipment is in good condition and rated to lift at least 200kg.
- 2. Affix the sling or chain to the lifting eye at the top of the mast.
- 3. Use one person to operate the lifting equipment, and at least one other person to hold the machine steady and watch for hazards.
- 4. Slowly lift, move and lower the machine into place, ensuring it remains fully upright.
- The standard Ezi-MT service weight is approximately 110kg.
- Never stand or reach underneath the machine while it is being lifted.

6.3 Transportation

Carry out the following procedure when preparing the Ezi-MT for transport:

- 1. Where possible, transport the machine lying in a horizontal position.
- 2. If the machine must be transported upright, apply both foot-brakes.
- 3. Tie the machine into place with strops rated for at least 500kg.
- Only use marked tie-down points to secure the machine.
- Ensure the machine is securely fastened against lateral forces from any direction.

6.4 Storage

If the machine is not to be used for a period of two months or more, it should be stored in a clean, dry place with good ventilation, at temperatures not below 0°C. Before placing the machine into storage, carry out the following procedures:

- 1. Lower the cradle to the ground.
- 2. Clean the machine thoroughly.
- 3. Using a silicone spray, lightly lubricate the winch mechanism and inside of the mast.

7 Safety Inspections

It is recommended to conduct regular safety inspections of the Ezi-MT. This helps to ensure operator safety and extend the service life of the machine.

- A Simpro strongly recommends that safety inspections are carried out according to the schedule described in this section.
- A Operators should immediately stop using the machine and request an inspection if any fault or abnormal operation is observed.
- A Suitable Personal Protective Equipment (PPE) should be worn when carrying out safety inspections.

7.1 Monthly inspection checklist

	Monthly Inspection Checklist								
Category	No.	Item	Check						
General	1	Entire machine	Visually inspect for dented or broken parts. Conduct a complete tipping cycle and check for any jams, faults, or abnormal behaviour.						
General	2	Cradle	Intact and securely fixed.						
	3	Guard panel	Intact and securely fixed.						
Safety systems	4	Braked winch	Check that the winch does not allow the cradle to descend without operator input, even with a full bin.						
	5	Labels	All warnings labels, guides etc are attached and legible.						
	6	Inside mast	Lightly lubricate with silicone spray.						
	7	Pivot roller	Lightly lubricate with silicone spray.						
Mechanical systems	8	Cradle axle	Lightly lubricate with silicone spray.						
	9	Tipping guide flap	Undamaged and moving freely.						
	10	Castor wheels	All castors running smoothly, both brakes working.						

7.2 Monthly inspection log

Date	Service Person	Location	Checks complete	Notes on repairs or maintenance required	Parts and materials used

8 Spare Parts

The following table includes only the most common parts. An illustrated list of parts may be viewed on our website here: https://simpro.world/bin-lifters/ezi-mt/spare-parts.

Diagram Ref.	Part Number	Description
-	1000000155	Cradle base pressing
-	1000000176	Nylon lifting strap with hook
-	100000179	Strap tension nut
-	1000000388	Wheel alignment sticker for cradle
-	1000000422	Braked winch
-	0000020014	Square plastic end cap
-	0000020019	Plastic handgrip
-	0060010001	Steel bush for roller
-	0090120000	Arm roller
-	0090120001	Mast sliding block
-	0230040001	Tip guide flap
-	0250040066	Castor wheel, no brake
-	0250040076	Castor wheel with brake
-	0250060016	30mm shaft collar
-	0250190453	Gas strut
-	1000000164	Frame brace strip

9 Warranty

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The conditions detailed below are a summary only. A full "Warranty Terms and Conditions" document is available on request.

Ezi-MT bin-tippers are warranted by the manufacturer against faulty workmanship and defective materials for a period of 12 months from the date of purchase.

Such warranty is subject to the following conditions:

- Under the terms of this warranty, the manufacturer agrees to repair or replace, at his
 own discretion, any parts that fail due to poor workmanship or faulty materials. It does
 not extend to any other loss or damage including consequential loss or damage or
 loss to other property or persons.
- 2. Without limiting the generality of paragraph 1 above, this warranty does not cover the following:
 - a. Travel expenses or freight.
 - b. Damage caused by accident, misuse or abuse.
 - c. Damage to any goods which have been altered or modified by someone other than the manufacturer or its authorised agent.
 - d. Damage or loss to the goods due to their unsuitability for any particular use.
- 3. Faults or breakdowns should be reported to the dealer who supplied the machine. No claims will be recognised unless authorisation is obtained from the manufacturer before any repairs are done.

This warranty shall be interpreted according to the laws of New Zealand and the parties agree to submit to the jurisdiction of the Courts of New Zealand.

Simpro has been inventing, perfecting and manufacturing materials handling solutions for over thirty years. From humble beginnings as a small engineering firm in Auckland, New Zealand, the company has grown to become a leading supplier of handling equipment for niche applications – such as bin lifting, tipping and handling equipment, pallet trucks and materials handling elevators.

Simpro products play an unobtrusive but essential role for thousands of companies around the world, in industries as diverse as waste

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management, food processing, resource extraction and pharmaceutical manufacturing. They are available through a network of agents which spans the globe, and are backed by a sophisticated in-house design and fabrication capability.

Simpro is a family-owned company, registered with the New Zealand Companies Office as Simpro Handling Equipment Ltd, company no. 1827916.

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